

# Absolute encoders – singleturn

**Compact magnetic**

**Sendix M3651A / M3671A (shaft / hollow shaft) Analog**



The Sendix M3651A and Sendix M3671A singleturn encoders with analog interface and magnetic sensor technology are particularly flexible in use due to their diverse interfaces and measuring ranges.

A green LED as reference point and a red LED as error indicator simplify both installation and error diagnosis.



Safety-Lock™



High rotational speed



Temperature range  
-40°... +85°C



High protection level  
IP



High shaft load capacity



Shock / vibration resistant



Reverse polarity protection



Surface protection salt spray tested optional

## Reliable and insensitive

- Sturdy bearing construction in Safety-Lock™ design for resistance against vibration and installation errors.
- Reduced number of components ensures magnetic insensitivity.
- IP67 protection and wide temperature range -40 °C ... +85 °C.

## Application oriented

- Current output 4 ... 20 mA.
- Voltage output 0 ... 10 V or 0 ... 5 V.
- Different measuring ranges.
- Set input for easy start-up.

**Order code**  
**Shaft version**

**8.M3651A.XXXX.XXX2**  
Type

If for each parameter of an encoder the underlined preferred option is selected, then the delivery time will be 10 working days for a maximum of 10 pieces. Qts. up to 50 pcs. of these types generally have a delivery time of 15 working days.



### a Flange

- 1 = clamping flange, IP67, ø 36 mm [1.42"]
- 3 = clamping flange, IP65, ø 36 mm [1.42"]
- 2 = synchro flange, IP67, ø 36 mm [1.42"]
- 4 = synchro flange, IP65, ø 36 mm [1.42"]

### b Shaft (ø x L), with flat

- 1 = ø 6 x 12.5 mm [0.24 x 0.49"]
- 3 = ø 8 x 15 mm [0.32 x 0.59"]
- 5 = ø 10 x 20 mm [0.39 x 0.79"]
- 2 = ø 1/4" x 12.5 mm [0.49"]

### c Output circuit <sup>1)</sup>

- 3 = current output
- 4 = voltage output

### d Type of connection

- 1 = axial cable, 1 m [3.28'] PVC
  - A = axial cable, special length PVC \*)
  - 2 = radial cable, 1 m [3.28'] PVC
  - B = radial cable, special length PVC \*)
  - 3 = axial M12 connector, 5-pin
  - 4 = radial M12 connector, 5-pin
- \*) Available special lengths (connection types A, B):  
2, 3, 5, 8, 10, 15 m [5.56, 9.84, 16.40, 26.25, 32.80, 49.21']  
order code expansion .XXXX = length in dm  
ex.: 8.M3651A.433A.3112.0030 (for cable length 3 m)

### e Interface / resolution / supply voltage

- 3 = 4 ... 20 mA / 12 bit / 10 ... 30 V DC
- 4 = 0 ... 10 V / 12 bit / 15 ... 30 V DC
- 5 = 0 ... 5 V / 11 bit / 10 ... 30 V DC

### f Measuring range

- 1 = 1 x 360°
- 2 = 1 x 180°
- 3 = 1 x 90°
- 4 = 1 x 45°

### g Counting direction

- 1 = cw
- 2 = ccw

*Optional on request*

- Ex 2/22 (only for connection types 3 and 4)
- surface protection salt spray tested

1) Output circuit "3" only in conjunction with interface "3", output circuit "4" only in conjunction with interface "4" or "5".

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**Compact magnetic**

**Sendix M3651A / M3671A (shaft / hollow shaft) Analog**

**Order code  
Hollow shaft**

**8.M3671A.XXXX.XXX2**  
Type

If for each parameter of an encoder the underlined preferred option is selected, then the delivery time will be 10 working days for a maximum of 10 pieces.  
Qts. up to 50 pcs. of these types generally have a delivery time of 15 working days.



- a** Flange  
2 = with stator coupling, IP65, ø 46 mm [1.81"]  
 3 = with spring element, long, IP65  
 5 = with stator coupling, IP67, ø 46 mm [1.81"]  
 6 = with spring element, long, IP67

- b** Blind hollow shaft  
 (insertion depth max. 18.5 mm [0.73"])  
 1 = ø 6 mm [0.24"]  
 3 = ø 8 mm [0.32"]  
4 = ø 10 mm [0.39"]  
 2 = ø 1/4"

- c** Output circuit <sup>1)</sup>  
3 = current output  
4 = voltage output

- d** Type of connection  
 1 = axial cable, 1 m [3.28'] PVC  
 A = axial cable, special length PVC \*)  
 2 = radial cable, 1 m [3.28'] PVC  
 B = radial cable, special length PVC \*)  
 3 = axial M12 connector, 5-pin  
4 = radial M12 connector, 5-pin  
 \*) Available special lengths (connection types A, B):  
 2, 3, 5, 8, 10, 15 m [5.56', 9.84', 16.40', 26.25', 32.80', 49.21']  
 order code expansion .XXXX = length in dm  
 Ex.: 8.M3671A.243A.3112.0030 (for cable length 3 m)

- e** Interface / resolution / supply voltage  
3 = 4 ... 20 mA / 12 bit / 10 ... 30 V DC  
4 = 0 ... 10 V / 12 bit / 15 ... 30 V DC  
 5 = 0 ... 5 V / 11 bit / 10 ... 30 V DC

- f** Measuring range  
1 = 1 x 360°  
 2 = 1 x 180°  
 3 = 1 x 90°  
 4 = 1 x 45°

- g** Counting direction  
1 = cw  
2 = ccw

Optional on request

- Ex 2/22 (only for connection types 3 and 4)
- surface protection salt spray tested

## Mounting accessory for shaft encoders

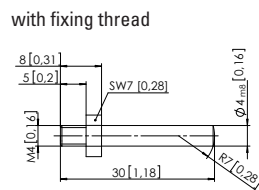
**Coupling** Bellows coupling ø 19 mm [0.75"] for shaft 8 mm [0.32"]

Order no.

**8.0000.1102.0808**

## Mounting accessory for hollow shaft encoders Dimensions in mm [inch]

**Cylindrical pin, long**  
 for flange with spring element  
 (flange type 3 + 6)



Order no.

**8.0010.4700.0000**

## Cables and connectors

**Preassembled cables** M12 female connector with coupling nut, 5-pin, A coded, straight open ended  
 2 m [6.56'] PVC cable

Order no.

**05.00.6081.2211.002M**

**Connectors** M12 female connector with coupling nut, 5-pin, A coded, straight (metal)

**8.0000.5116.0000**

Further Kübler accessories can be found at: [kuebler.com/accessories](http://kuebler.com/accessories)

Further Kübler cables and connectors can be found at: [kuebler.com/connection-technology](http://kuebler.com/connection-technology)

1) Output circuit "3" only in conjunction with interface "3", output circuit "4" only in conjunction with interface "4" or "5".

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## Technical data

Electrical characteristics current interface 4 ... 20 mA		
<b>Supply voltage</b>	10 ... 30 V DC	
<b>Current consumption (no load)</b>	max. 30 mA	
<b>Reverse polarity protection of the supply voltage</b>	yes	
<b>Short-circuit proof outputs</b>	yes <sup>1)</sup>	
<b>Measuring range</b>	45°, 90°, 180° or 360°	
<b>DA converter resolution</b>	12 bit	
<b>Singleturn accuracy, at 25°C [77°F]</b>	±1°	
<b>Temperature coefficient</b>	< 100 ppm/K	
<b>Repeat accuracy, at 25°C [77°F]</b>	±0.2°	
<b>Output load</b>	at 10 V DC at 24 V DC at 30 V DC	max. 200 Ohm max. 900 Ohm max. 1200 Ohm
<b>Setting time</b>	< 1 ms, R <sub>Burden</sub> = 900 Ohm, 25°C [77°F]	
<b>LEDs (green/red)</b>	<ul style="list-style-type: none"> <li>- system status</li> <li>- current loop interruption – input load too high</li> <li>- reference point display (only with factory settings)</li> <li>at cw: betw. 0° and 1°</li> <li>at ccw: betw. 0° and -1°</li> </ul>	
<b>SET input</b>	level = +V for 1 s minimum	
<b>PowerON Time</b>	< 1 s	
<b>Update rate</b>	1 ms	

Electrical characteristics voltage interface 0 ... 10 V / 0 ... 5 V		
<b>Supply voltage</b>	output 0 ... 5 V output 0 ... 10 V	10 ... 30 V DC 15 ... 30 V DC
<b>Current consumption (no load)</b>	max. 30 mA	
<b>Reverse polarity protection of the supply voltage</b>	yes	
<b>Short-circuit proof outputs</b>	yes <sup>1)</sup>	
<b>Measuring range</b>	45°, 90°, 180° or 360°	
<b>DA converter resolution</b>	0 ... 10 V 0 ... 5 V	12 bit 11 bit
<b>Singleturn accuracy, at 25°C [77°F]</b>	±1°	
<b>Temperature coefficient</b>	< 100 ppm/K	
<b>Repeat accuracy, at 25°C [77°F]</b>	±0.2°	
<b>Current output</b>	max. 10 mA	
<b>Setting time</b>	< 1 ms, R <sub>Load</sub> = 1000 Ohm, 25°C [77°F]	
<b>LEDs (green/red)</b>	<ul style="list-style-type: none"> <li>- system status</li> <li>- reference point display (only with factory settings)</li> <li>at cw: betw. 0° and 1°</li> <li>at ccw: betw. 0° and -1°</li> </ul>	
<b>SET input</b>	level = +V for 1 s minimum	
<b>PowerON Time</b>	< 1 s	
<b>Update rate</b>	1 ms	

Mechanical characteristics	
<b>Maximum speed</b>	shaft or blind hollow shaft version without shaft seal (IP65) 6000 min <sup>-1</sup> 3000 min <sup>-1</sup> (continuous)
	shaft or blind hollow shaft version with shaft seal (IP67) 4000 min <sup>-1</sup> 2000 min <sup>-1</sup> (continuous)
<b>Starting torque at 20 °C [68 °F]</b>	without shaft seal < 0.007 Nm with shaft seal (IP67) < 0.01 Nm
<b>Shaft load capacity</b>	radial 40 N axial 20 N
<b>Weight</b>	approx. 210 g [7.41 oz]
<b>Protection acc. to EN 60529</b>	IP65 or IP67
<b>Working temperature range</b>	-40 °C ... +85 °C [-40 °F ... +185 °F]
<b>Materials</b>	shaft / hollow shaft stainless steel flange aluminum housing zinc die-cast cable PVC
<b>Shock resistance acc. to EN 60068-2-27</b>	2500 m/s <sup>2</sup> , 6 ms
<b>Vibration resistance acc. to EN 60068-2-6</b>	300 m/s <sup>2</sup> , 10 ... 2000 Hz

SET input	
<b>Input</b>	active HIGH
<b>Input type</b>	comparator
<b>Signal level</b>	HIGH min. 60 % of +V, max: +V LOW max. 30 % of +V (+V = supply voltage)
<b>Input current</b>	< 0.5 mA
<b>Min. pulse duration (SET)</b>	10 ms
<b>Input delay</b>	1 ms
<b>New position data readable after</b>	1 ms
<b>Internal processing time</b>	200 ms
<p>The encoder can be set to zero at any position by means of a HIGH signal on the SET input. Other preset values can be factory-programmed. The SET input has a signal processing time of approx. 1 ms, after which the new position data can be read. Once the SET function has been triggered, the encoder requires an internal processing time of typ. 200 ms; during this time the supply voltage must not be switched off.</p> <p>The SET function should be carried out whilst the encoder is at rest.</p> <p>The number of preset value writing cycles is limited to 10,000.</p> <p>If this input is not used, it should be connected to 0 V (Encoder ground GND) in order to avoid interferences.</p>	

Approvals	
<b>E1 compliant</b> in accordance with	ECE guideline
<b>UL compliant</b> in accordance with	File no. E224618
<b>CE compliant</b> in accordance with	EMC Directive 2014/30/EU RoHS Directive 2011/65/EU ATEX Directive 2014/34/EU (for Ex 2/22 variants)
<b>UKCA compliant</b> in accordance with	EMC Regulations S.I. 2016/1091 RoHS Regulations S.I. 2012/3032 UKEX Regulations S.I. 2016/1107 (for Ex 2/22 variants)

1) When the supply voltage is correctly applied.  
But not output to +V. Supply voltage and sensor output signal are not galvanically isolated.

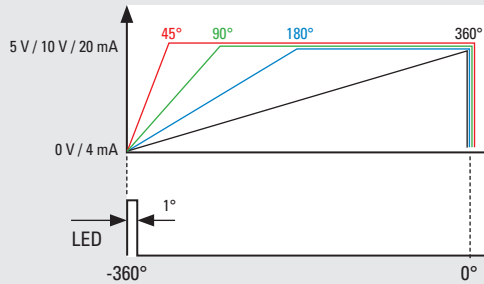
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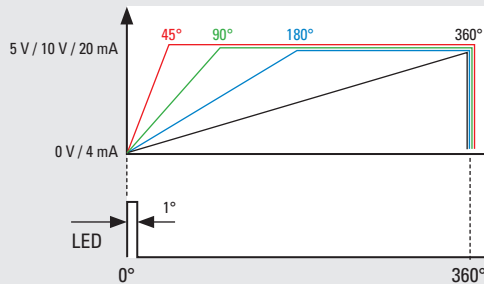
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**Example (output signal evolution)  
Variante counting direction cw**

**Direction of rotation left**

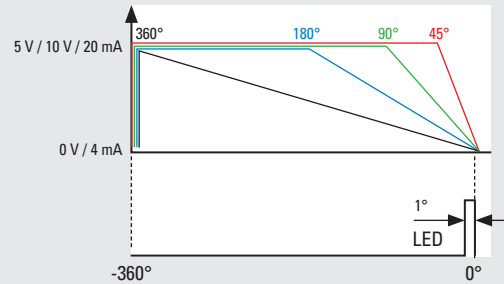


**Direction of rotation right**

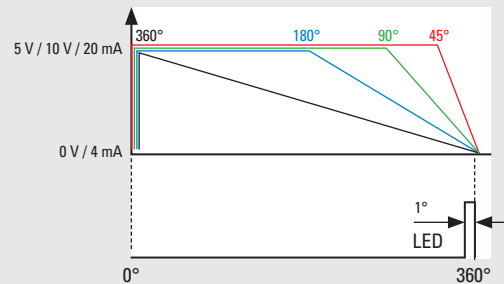


**Example (output signal evolution)  
Variante counting direction ccw**

**Direction of rotation left**



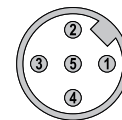
**Direction of rotation right**



## Terminal assignment

Interface 3 (current)	Type of connection 1, 2, A, B	Cable (isolate unused cores individually before initial start-up)					
		Signal:	0 V	+V	+I	SET	-
		Core color:	WH	BN	GN	GY	PK
Interface 3 (current)	Type of connection 3, 4	M12 connector, 5 pin					
		Signal:	0 V	+V	+I	SET	-
		Pin:	3	2	1	5	4
Interface 4, 5 (voltage)	Type of connection 1, 2, A, B	Cable (isolate unused cores individually before initial start-up)					
		Signal:	0 V	+V	+U	SET	-
		Core color:	WH	BN	GN	GY	PK
Interface 4, 5 (voltage)	Type of connection 3, 4	M12 connector, 5 pin					
		Signal:	0 V	+V	+U	SET	-
		Pin:	3	2	1	5	4

**Top view of mating side, male contact base**



M12 connector, 5-pin

- +V: Supply voltage encoder +V DC
- 0 V: Supply voltage encoder ground GND (0 V)
- +U: Voltage
- +I: Current
- SET: Set input

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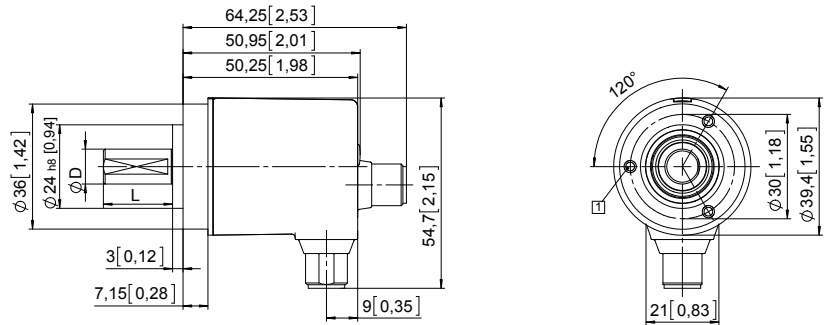
## Dimensions shaft version

Dimensions in mm [inch]

### Clamping flange, $\varnothing$ 36 [1.42]

Flange type 1 and 3

1 3 x M3, 6 [0.24] deep

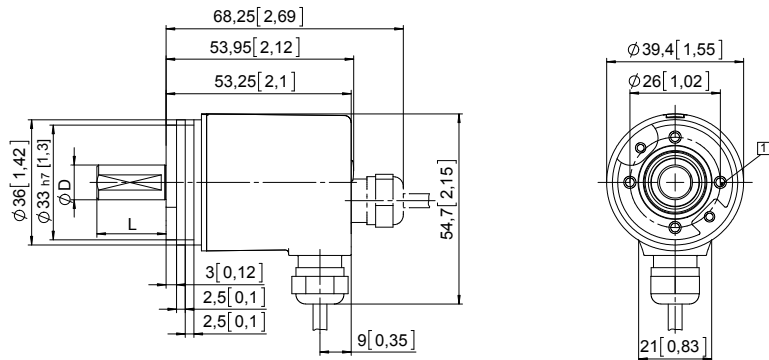


D	Fit	L
6 [0.24]	h7	12.5 [0.49]
8 [0.32]	h7	15 [0.59]
10 [0.39]	f7	20 [0.79]
1/4"	h7	12.5 [0.49]

### Synchro flange, $\varnothing$ 36 [1.42]

Flange type 2 and 4

1 4 x M3, 6 [0.24] deep



D	Fit	L
6 [0.24]	h7	12.5 [0.49]
8 [0.32]	h7	15 [0.59]
10 [0.39]	f7	20 [0.79]
1/4"	h7	12.5 [0.49]

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## Dimensions hollow shaft version

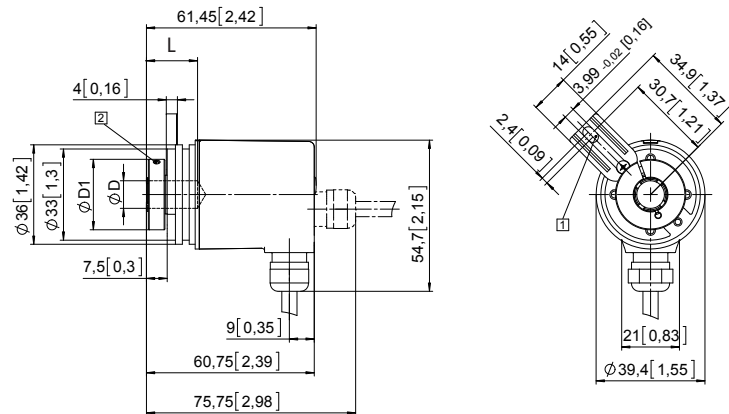
Dimensions in mm [inch]

### Flange with spring element, long Flange type 3 and 6

- 1 Slot spring element, recommendation: cylindrical pin DIN 7,  $\varnothing 4$  [0.16]
- 2 Recommended torque for the clamping ring 0.7 Nm

D	Fit	L	D1
6 [0.24]	H7	18.5 [0.73]	24 [0.94]
8 [0.32]	H7	18.5 [0.73]	25.5 [1.00]
10 [0.39]	H7	18.5 [0.73]	25.5 [1.00]
1/4"	H7	18.5 [0.73]	24 [0.94]

L = insertion depth max. blind hollow shaft



### Flange with stator coupling, $\varnothing 46$ [1.81] Flange type 2 and 5

- 1 Recommended torque for the clamping ring 0.7 Nm

D	Fit	L	D1
6 [0.24]	H7	18.5 [0.73]	24 [0.94]
8 [0.32]	H7	18.5 [0.73]	25.5 [1.00]
10 [0.39]	H7	18.5 [0.73]	25.5 [1.00]
1/4"	H7	18.5 [0.73]	24 [0.94]

L = insertion depth max. blind hollow shaft

